An Ambiguity Function Independent of Assumptions About Bandwidth and Carrier Frequency

D. A. SWICK

Electronics Branch
Sound Division

December 15, i966

ARCHIVE COPY





NAVAL RESEARCH LABORATORY Washington, D.C.

DISTRIBUTION OF THIS DOCUMENT IS UNLIMITED

An Ambiguity Function Independent of Assumptions About Bandwidth and Carrier Frequency

į

D. A. SWICK

Electronics Branch
Sound Division

Abstract: With the use of a mean-square difference criterio 1 to distinguish echoes from two targets at different ranges moving with different velocities, an ambiguity function is derived. The concept of a modulated carrier is avoided, and the actual Doppler effect of time compression or expansion is used, rather than the more usual approximation of constant frequency shift. Thus this function can be applied to the very-low-low broadband signals sometimes employed in sonar systems. It reduces to the Woolat and ambiguity function in the care of two targets of nearly equal velocity, and, in general, in a narrow-band approximation. Some properties of this ambiguity function are discussed.

INTRODUCTION

The ambiguity function has been used by Woodward (1) and others (2-7) to study range and velocity resolution of radar and sonar targets. In most of this work, the Doppler effect has been approximated by a frequency shift, which is valid for narrow-band signals. Cahlander (8) has used statistical detection theory to study the wideband signals used by bats for echolocation; Kelly and Wishner (9) have extended the theory to include the effects of high velocity and accelerating targets. Their ambiguity function reduces to that of Woodward for narrow-band signals, if terms of the order of $\exp(\pm 2i\omega_0 t)$ are neglected.

By means of a simplified model for the echo of a signal from a moving target, a mean-square criterion is used to derive an ambiguity function. This function can be used to study the resolution of echoes from two such targets. It is equivalent to the "signal function" of Cahlander (8), although the derivation and application are quite different, and to the ambiguity function of Kelly and Wishner (9). Here, however, neither bandwidth nor carrier frequency enter into the derivation. In the case of sonar signals, the velocity of the target v need not be very small relative to the velocity of propagation of the signal c; all that is required is that v < c. By suitable identification of parameters, the new ambiguity function can be identified with Woodward's function in the case of two targets of nearly equal velocities, and in the narrow-band approximation to the detection of echoes from a single target.

THE DOPPLER EFFECT MODEL

Let s(t) be a real-valued function, square integrable on $(-\infty, \infty)$, representing a signal transmitted with a propagation velocity c, assumed constant. Let r(t) be the radial distance and v be the velocity (assumed radial and constant) of a reflecting object. The signal portion of the received (reflected) waveform is then

$$x(t) = a s[t - T(t)], \qquad (1)$$

where a is a constant (possibly complex to account for phase change on reflection) and T(t) is the time required for the signal to reach the object and return. Thus, a signal received at

NRI. Problem S01-06; Project RF 101-03-44-4054. This is an interim report; work is continuing on this problem. Manuscript submitted August 8, 1966.

time t was transmitted at time t - T(t), and was incident on the target at time t - T(t)/2, when the target position was $r_0 + vt - vT(t)/2$. Hence,

$$cT(t)/2 = r_0 + vt - vT(t)/2$$

or

$$T(t) = \frac{2(r_0 + vt)}{\varepsilon + v}, \tag{2}$$

and, from this,

$$x(t) = a s(\alpha t - T_0), \tag{3}$$

where

$$\alpha = \frac{c - v}{c + v} \tag{4}$$

is the "Doppler stretch factor" and

$$T_0 = \frac{2r_0}{c+v} \tag{5}$$

is the delay of the signal at t = 0.

THE AMBIGUITY FUNCTION

If there is another target with radial velocity v' at a radial distance $r'(t) = r'_0 + v't$, the signal reflected from it will be

$$x'(t) = a's(\alpha't - T_0') \tag{6}$$

where the constants are defined as before. We wish to distinguish the waveforms given by Eqs. (3) and (6). Hence, following Woodward (1), we would like their mean-squared difference

$$\int_{-x}^{x} [x(t) - x'(t)]^{2} dt \tag{7}$$

to be as large as possible for all values of the parameters, except, of course, in a small region near x(t) = x'(t), when the targets are in fact indistinguishable.

Expanding Eq. (7) we get

$$\int_{-x}^{x} [x(t) - x'(t)]^{2} dt = \int_{-x}^{x} x^{2}(t) dt + \int_{-x}^{x} x'^{2}(t) dt - 2 \int_{-x}^{x} x(t)x'(t) dt$$

$$= a^{2} \int_{-x}^{x} s^{2}(\alpha t - T_{0}) dt + a'^{2} \int_{-x}^{x} s^{2}(\alpha' t - T'_{0}) dt$$

$$- 2aa' \int_{-x}^{x} s(\alpha t - T_{0}) s(\alpha' t - T'_{0}) dt$$

$$= \frac{\alpha' a^{2} + \alpha a'^{2}}{\alpha \alpha'} - 2aa' \int_{-x}^{x} s(\alpha t - T_{0}) s(\alpha' t - T'_{0}) dt, \qquad (8)$$

where we assume the signal to be normalized so that

$$\int_{-\infty}^{\infty} s^2(t) \ dt = 1.$$

Since the first term on the right of Eq. (8) does not depend on the signal waveform, and since a and a' may be complex, we see that we can maximize Eq. (7) by choosing a signal which minimizes the modulus of the second term on the right in Eq. (8).

Equivalently, we can define the correlation function

$$\theta(\tau,\gamma) \triangleq \int_{-\infty}^{\infty} s(t) \ s(\gamma t + \tau) \ dt, \tag{9}$$

where either

$$\gamma = \frac{\alpha'}{\alpha}$$
 and $\tau = \frac{\alpha'}{\alpha} T_0 - T_0'$ (10)

or

$$\gamma = \frac{\alpha}{\alpha'}$$
 and $\tau = \frac{\alpha}{\alpha'} T_0 - T_0$, (11)

and require that $|\theta(\tau, \gamma)|$ be as small as possible except in the vicinity of

$$\theta(0, 1) = \int_{-\infty}^{\infty} s^{2}(t) dt = 1.$$
 (12)

Equation (12) represents, of course, the correlation of signals reflected from targets at the same range and with the same velocity.

If we define the ambiguity function as

$$\psi(\tau, \gamma) \triangleq |\theta(\tau, \gamma)|^2, \tag{13}$$

then the "distinguishability" criterion requires that $\psi(\tau, \gamma)$ be as small as possible except near $\psi(0, 1) = 1$. The functions $\theta(\tau, \gamma)$ and, hence, $\psi(\tau, \gamma)$ are independent of any assumptions about bandwidth and carrier frequency.

THE RELATIONSHIP TO THE WOODWARD AMBIGUITY FUNCTION

Let $\hat{s}(t)$ be the Hilbert transform of s(t). The "pre-envelope" of s(t) is defined by Dugundji (10) to be

$$z(t) = s(t) + i \hat{s}(t). \tag{14}$$

Then $s(t) = Re\{z(t)\}$, and Eq. (9) becomes

$$\theta(\tau, \gamma) = \int_{-\infty}^{\infty} Re\{z(t)\} Re\{z(\gamma t + \tau)\} dt$$

$$= (1/4) \int_{-\infty}^{\infty} [z(t) + z^{*}(t)] [z(\gamma t + \tau) + z^{*}(\gamma t + \tau)] dt$$

$$= (1/2) Re\{\int_{-\infty}^{\infty} z(t) z^{*}(\gamma t + \tau) + z(t) z(\gamma t + \tau) dt\}$$

$$= (1/2) Re\{\theta_{1}(\tau, \gamma) + \theta_{2}(\tau, \gamma)\}, \qquad (15)$$

where the asterisk denotes the complex conjugate

$$\theta_1(\tau, \gamma) = \int_{-\infty}^{\infty} z(t) \ z^*(\gamma t + \tau) \ dt, \tag{16}$$

and

$$\theta_2(\tau, \gamma) = \int_{-\infty}^{\infty} z(t) \ z(\gamma t + \tau) \ dt \,. \tag{17}$$

If, following Kelly and Wishner (9), we were to express s(t) as a modulated carrier,

$$s(t) = Re\{z(t)\} = Re\{[z(t)e^{-t\omega_0 t}]e^{t\omega_0 t}\}, \tag{18}$$

then $\theta_2(\tau, \gamma)$, Eq. (17), would be related to the terms of order $\exp(\pm 2i\omega_0 t)$ and could be neglected in a narrow-band approximation, as is done by them. We do not need to do this, however, for in fact $\theta_2(\tau, \gamma)$ vanishes identically. If

$$Z(\omega) = \int_{-\pi}^{\infty} z(t) e^{-i\omega t} dt$$

is the Fourier transform of z(t), then we can write

$$\theta_{z}(\tau, \gamma) = \frac{1}{4\pi^{2}} \iiint_{-\infty}^{\infty} Z(\omega) Z(\nu) e^{i(\nu + \gamma \omega)t} e^{i\omega\tau} dt d\nu d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} Z(\omega) Z(-\gamma \omega) e^{i\omega\tau} d\omega = 0,$$
(19)

since

$$Z(\omega) = 0, \omega < 0$$

and

$$Z(-\gamma\omega)=0$$
, $\omega>0$, for $\gamma>0$.

(See, for example, Refs. 10 and 11.)

We can write s(t) as in Eq. (18), where ω_0 is now an arbitrary parameter which may be, but does not have to be, associated with a "carrier." If we let $f(t) = z(t) \exp[-i\omega_0 t]$, Eq. (16) becomes

$$\theta_{1}(\tau, \gamma) = \int_{-\infty}^{\infty} f(t) e^{i\omega_{0}t} f^{*}(\gamma t + \tau) e^{-i\omega_{0}(\gamma t + \tau)} dt$$

$$= e^{-i\omega_{0}\tau} \int_{-\infty}^{\infty} f(t) f^{*}(\gamma t + \tau) e^{-i\phi t} dt$$

$$\approx e^{-i\omega_{0}\tau} \chi(\tau, \phi), \tag{20}$$

where

$$\phi = (\gamma - 1)\omega_0, \tag{21}$$

and

$$\chi(\tau, \, \phi) = \int_{-\tau}^{\infty} f(t) \, f^*(t+\tau) \, e^{-i\phi t} \, dt \tag{22}$$

is the combined time and frequency correlation function of Woodward (1). The approximation in Eq. (20) holds in the case of two targets of nearly equal velocity. It requires, of course, that f(t) be slowly varying as compared to $\exp(-i\phi t) = \exp[-i(\gamma - 1)\omega_0 t]$, but it must be remembered that ω_0 is arbitrary.

If we consider the echo from one target (i.e., let $a' = \alpha' = 1$, $T'_0 = 0$), and if we identify ω_0 with a single transmitted frequency, then ϕ is the actual Doppler shift of this single frequency. It is a constant, but no assumptions have been made about the constancy of Doppler shift across a band of frequencies.

From Eqs. (13), (15), (19), and (20), we have

$$\psi(\tau, \gamma) = (1/4) |Re\{\theta_1(\tau, \gamma)\}|^2 \le (1/4) |\theta_1(\tau, \gamma)|^2 \approx (1/4) |\psi(\tau, \phi)|, \tag{23}$$

where ϕ is given by Eq. (21), and

$$\psi(\tau, \phi) = |\chi(\tau, \phi)|^2 \tag{24}$$

is the Woodward ambiguity function.

SOME PROPERTIES OF THIS AMBIGUITY FUNCTION

By analogy with the properties of the Woodward ambiguity function, as discussed by Siebert (12) and others, some of the properties of the new function can be summarized.

If

$$S(\omega) = \int_{-\infty}^{\infty} s(t)e^{-i\omega t} dt$$

is the Fourier transform of s(t), we can write for Eq. (9)

$$\theta(\tau, \gamma) = \frac{1}{4\pi^2} \iiint_{-\infty}^{\infty} S(\nu) \ S(\omega) \ e^{i(\nu + \gamma \omega)t} \ e^{i\omega\tau} \ d\omega \ d\nu \ dt$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) \ S(-\gamma \omega) \ e^{i\omega\tau} \ d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) \ S^*(\gamma \omega) \ e^{i\omega\tau} \ d\omega, \tag{25}$$

since s(t) is real.

By consideration of

$$\int_{-\tau}^{\tau} [s(t) - \lambda s(\gamma t + \tau)]^2 dt \ge 0$$
 (26)

for all λ , and, in particular, Eq. (26) ≥ 0 for $\lambda = \sqrt{\gamma} \operatorname{sgn} \theta(\tau, \gamma)$, it follows that

$$\theta(\tau, \gamma) \leq \frac{1}{\sqrt{\gamma}}, \text{ for all } \tau, \gamma$$
 (27)

and

$$\theta(\tau, \gamma) \le 1$$
, for all τ , for $\gamma \ge 1$. (28)

Integration of $\theta^2(\tau, \gamma)$ over all values of its parameters must be limited to at most $0 < \gamma < \infty$, as pointed out by Cahlander (8), who shows, as do Kelly and Wishner (9), that the usual volume constraint on the ambiguity function must be replaced by

$$\int_0^\infty \int_{-\infty}^\infty \theta^2(\tau, \gamma) \ d\tau \ d\gamma = \int_0^\infty \frac{1}{\omega} |S(\omega)|^2 \ d\omega. \tag{29}$$

Here $|S(\omega)|^2$ must vanish sufficiently rapidly as $\omega \to 0$ so that the integral in Eq. (29) exists (9). Equation (29) is not independent of signal waveform as is the equivalent integration of the Woodward ambiguity function. In a narrow-band approximation, however, the integral reduces to π/ω_0 , a constant (8,9).

In place of the twofold symmetry axis of the Woodward function, we have for $\gamma \neq 0$

$$\theta\left(-\frac{\tau}{\gamma}, \frac{1}{\gamma}\right) = \int_{-\infty}^{\infty} s(t) \ s\left(\frac{t}{\gamma} - \frac{\tau}{\gamma}\right) dt = \gamma \int_{-\infty}^{\infty} s(t) \ s(\gamma t + \tau) \ dt$$
$$= \gamma \theta(\tau, \gamma), \tag{30}$$

which shows the relationship between the alternative definitions of the parameters τ and γ , given in Eqs. (10) and (11).

In the case $\gamma = 1$, Eq. (9) becomes

$$\theta(\tau, 1) = \int_{-\tau}^{x} s(t) \ s(t+\tau) \ dt = R(\tau),$$

an autocorrelation function of s(t); and Eq. (16) becomes an autocorrelation function of the "pre-envelope" z(t).

The Woodward ambiguity function is related to the output of a filter matched to a signal s(t), in response to a signal $s(t-\tau) \exp(-i\phi t)$, i.e., an echo with a constant time delay and a constant frequency shift (13). Similarly, the last term on the right of Eq. (8), and hence Eq. (9), is, apart from a constant multiplier, the output of a filter matched to $s(\alpha t - T_0)$ when the input is $s(\alpha't - T_0')$ (9), evaluated at the time the output peak signal power occurs. If we let a' = a' = 1 and $T_0' = 0$, then $\theta(\tau, \gamma) = \theta(-T_0, \alpha)$ is the output of a filter matched to the transmitted signal, when the input is an echo from a moving target. Each frequency, ω , in the transmitted signal has been shifted by an amount proportional to itself, i.e., is received as $\omega_d = \alpha \omega$, where α is given by Eq. (4).

ACKNOWLEDGMENT

The author would like to thank W. J. Finney and Dr. H. A. Hauptman of the Naval Research Laboratory for helpful discussions, and Dr. J. L. Brown, Jr. of Ordnance Research Laboratory, Pennsylvania State University, for a grounding in the mathematics of signal theory.

REFERENCES

- 1. Woodward, P.M., "Probability and Information Theory, with Applications to Radar," 2nd edition, London: Pergamon, 1964
- Elspas, B., "A Radar System Based on Statistical Estimation and Resolution Considerations," Stanford Electronics Laboratories, Stanford University, Technical Report 361-1, Aug. 1, 1955
- 3. Siebert, W.M., "A Radar Detection Philosophy," IRE Trans. on Inform. Theory IT-2:204-221 (Sept. 1956)
- 4. Stewart, J.L., and Westerfield, E.C., "A Theory of Active Sonar Detection," Proc. IRE 47:872-881 (May 1959)
- 5. Westerfield, E.C., Prager, R.H., and Stewart, J.L., "Processing Gains Against Reverberation (Clutter) Using Matched Filters," IRE Trans. on Inform. Theory IT-6:342-348 (June 1960)

- 6 Urkowitz, H., Hauer, C.A., and Koval, J.F., "Generalized Resolution in Radar Systems," Proc IRE 50:2093 3705 (1962)
- 7. Remley, W.R., "Doppler Dispersion Effects in Matched Filter Detection and Resolution," *Proc. IEEE* 54:33-39 (Jan. 1966)
- 8 Cahlander, D.A., "Echolocation with Wide-Band Waveforms Bat Sonar Signals," Lincoln Lab., MIT, Tec'inical Report 271, May 1364
- 9. Kelly, E.J., and Wishner, R.P., "Matched-Filter Theory for High-Velocity, Accelerating Targets," IEEE Trans on Military Electron Mil-9:56-69 (Jan. 1965)
- 10 Dugundji, J., "Envelopes and Pre-Envelopes of Real Waveforms," IRE Trans. on Inform. Theory IT-4:53-57 (Mar. 1958)
- 11 Stutt, C.A., "A Note on Invariant Relations for Ambiguity and Distance Functions," IRE Trans on Inform Theory 1T-5:164-167 (Dec. 1959)
- 12. Siebert, W.M., "Studies of Woodward's Uncertainty Function," Quart. Progress Rept., MIT, Cambridge, Mass., pp. 90-94 (Apr. 1958)
- 13. Turin, G.L., "An Introduction to Matched Filters," IRE Trans on Inform. Theory IT-6:311-329 (June 196.))

Security Classification									
DOCUMENT CONT	ROL DATA - R	& D							
Security classification of fille, body of abstract and indexing	annotation must be e								
1 OHIGINATING ACTIVITY (Corporate author)		1	CURITY CLASSIFICATION						
Naval Research Laboratory		Unclassific	ed						
Washington, D.C. 20390		26 GROUP							
3 REPORT TITLE									
AN AMBIGUITY FUNCTION INDEPENDENT OF	ASSUMPTION	S ABOUT							
BANDWIDTH AND CARRIER FREQUENCY									
4 DESCRIPTIVE NOTES (Type of report and inclusive dates)	• •								
This is an interim report; work is continuing on this p	roblem.	- 							
5 AUTHORIS: (First name, middle initial, last name)									
D. A. Swick									
27. The wick									
	·		· .						
December 15, 1966	70. TOTAL NO O	_	76 NO OF REFS						
8a. CONTRACT OR GRANT NO	<u> </u>		13						
NRL Problem S01-06	9#. ORIGINATOR	REPORT NUME)ER(5)						
b. PROJECT NG	NRL Repor	NRL Report 6471							
RF 101-03-44-4054									
c.	25.55.55.55								
, ··	this report	R * NOTS: (Any of	her numbers that may be easigned						
4									
10 DISTRIBUTION STATEMENT	<u> </u>	·							
TO STATE OF TOWN STATEMENT									
Distribution of this document is unlimited.			j						
11 SJPPLEMENTARY NOTES	12 SPONSORING	MILITARY ACTIO							
	1	t of the Navy							
		laval Research							
	4	, D.C. 20360	•						
13 ARSTRACT	1								
What also were Comment and Michigan			v.a.						
With the use of a mean-square difference criterio									
ranges moving with different velocities, at ambiguit									
carrier is avoided, and the actual Doppler effect of time compression or expansion is used, rather than									
the more usual approximation of constant frequency	shift. Thus this	function can	be applied to the very-						
low-frequency broadband signals sometimes employ	ed in sonar sy:	stems. It redi	ices to the Woodward						
ambiguity function in the case of two targets of near			eral, in a narrow-band						
approximation. Some properties of this ambiguity fur	nction are discu	ssed.	j						
1									
			i						
			•						
DD FORM 1473 (PAGE 1)									

S/N 0101-807-6801 a.

Security Classification

Security Classification

MEY MOROS	LIN	LINKA		LINCS		LINK C	
KEY WORDS		W T	COLE WT		ROLE WT		
Radar targets							
Sonar targets	į						
Echo distinguishing						Ì	
Ambiguity function (Woodward)	į	İ			}	l	
Doppler effect	1						
Range							
Waves	į						
Pre-envelope							
Mathematical analysis				t			
	Į					1	
					ļ		
		1					
						i	
	ļ					l	
					<u> </u>	1	
	l						
	l					l	
						ļ.	
	j						
	ı					}	
	ı						
]						
	j				i		
]						
	1						
	Į į						
			Í				
]						
	ļ						
			ļ ļ				
	[
	[[
					j		
	1 1			1	1		

DD PORM 1473 (BACK)
(PAGE 2)

10

Security Classification